



NFPA Education and Technology Foundation Final Presentation Loyola Marymount University Dr. Emin Issakhanian 4/13/23



Team Introduction

- All senior capstone students
- All new to FPCV
- Excited to be participating!



Ambuj Bhatnagar



Cole Daniel







Alexis Mendez



Objectives



Design Objectives

- Qualify for all four events
- Maximize performance in sprint race

Hydraulic Circuit Objectives

- Five operating modes
- Design the circuit around the pump and motor

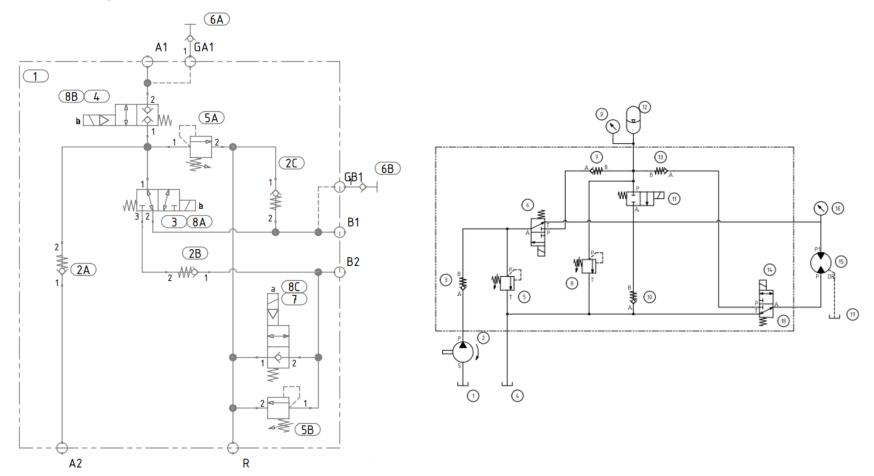
Vehicle Design Features

- Light-weight design (107 lbs w/ fluid):
 - Honeycomb composite sandwich material used for top and bottom deck
 - Additional weight savings: 1.5lb reservoir, 12lb accumulator
- 20" wheels for decreased rotational moment of inertia
- Gear shifting on front drivetrain for easy accumulator pressurization

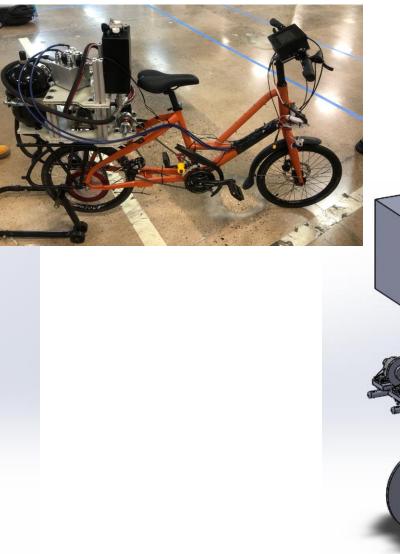
Hydraulic Circuit

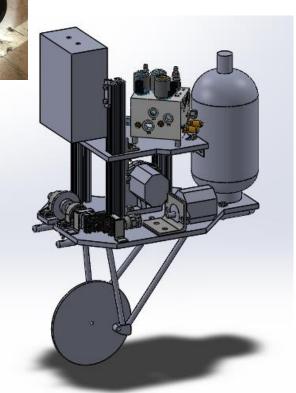


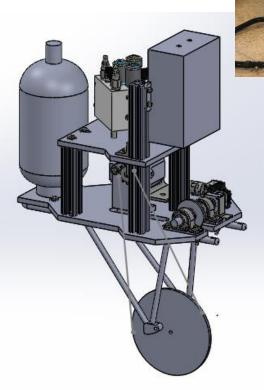
Last year's design implemented a 'coast mode', whereas this year we are implementing this 'boosted drive mode'













- Aluminum Honeycomb Core, Fiberglass Face composite sandwich used for mounting panels (high strength and low weight)
 - Oversized clearance holes used to give provide room for adjustment and perfect alignment during assembly
 - Oversized washers used to position components in oversized holes AND distribute load without deforming plate
- Vertical accumulator mounting for optimal discharge



Double-deck design with composite mounting panels



- 3-Speed chainring for multiple gear ratios
 - Front derailleur to switch between gears while pedalling
- Mount designed and manufactured for Shimano rear chain tensioner which came with the bike frame
- Front chain tensioner used to keep chain in correct orientation when going into the derailleur
 - Difficult to maintain correct position when full load on it so additional options were tested



Front chain tensioner





Rear chain tensioner



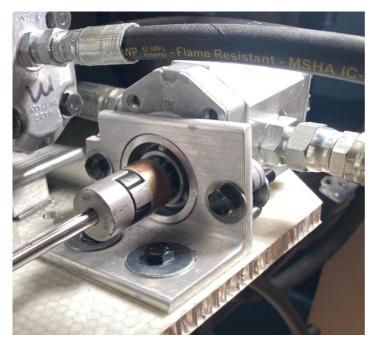
- 90 degree gearbox with built in 3:1 speed increaser to keep the design compact
- Freewheel sprocket allows rider to coast without pedaling
- Mounting for drivetrain components use spacers to maintain a consistent shaft height



90° gearbox and freewheel sprocket



- Fabricated custom pump and motor mounts when supplier couldn't fulfill order
 - Our machinist was already running behind schedule, so this further delayed assembly was rushed



Pump mount



Motor mount

Testing



- Hydraulic circuit testing
 - Listened to audio cues of manifold valves to test each mode.
 - No leaks found among all hose connections.
 - After testing on the rack, circuit in direct drive was deemed successful.
 - Live test performed with Brent as rider was successful.
 - Accumulator charge/discharge tested.
- Pump drivetrain testing
 - Implemented several front chain tensioners after first iteration failed.
 - First used clamping hub coupling on a keyway shaft. The shaft slid inside coupling, eliminating any power transmission. Resolved by replacing the clamping hub coupling with a set screw coupling.
- Motor drivetrain testing
 - Initial misalignment between motor sprocket and wheel sprocket. Shifted motor mount and cut new slots in honeycomb for chain travel.

Lessons Learned



- Integration and testing should be given a large portion of a project's schedule
 - Assembly take a great deal of time and working through integration issues is highly time consuming
- Engineering is a highly iterative process
 - Many design issues only come about once components are available and systems have been integrated

- Order parts as early as possible
 - Lead times can be long, and suppliers are sometimes unable to fulfill orders