

N F P A

Fluid Power

VEHICLE

Challenge



NFPA
Education and
Technology
Foundation

Final Presentation
Cal Poly
Dr. Jim Widmann
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CAL POLY

Intro



Connor Getz



Milo Klein



Joshua Romano



Marius Tali



Yael Valdez





Manufacturing

Vehicle Construction & Final Product

Overview



New bike chassis: Frame, Seat, and Handlebars

New Hydraulic Circuit Designed and Assembled

Experimentation with gear ratio's and shifting



Frame



- All frame pieces cut, welded and drilled on campus
 - All pieces TIG welded except for pedal and front wheel tubes
 - C-clamps and welding magnets were used as primary fixturing
 - Various amperages utilized for welding differing wall thicknesses
 - Pedal and front wheel tubes MIG welded
 - Cleaned and painted after manufacturing



Handlebars

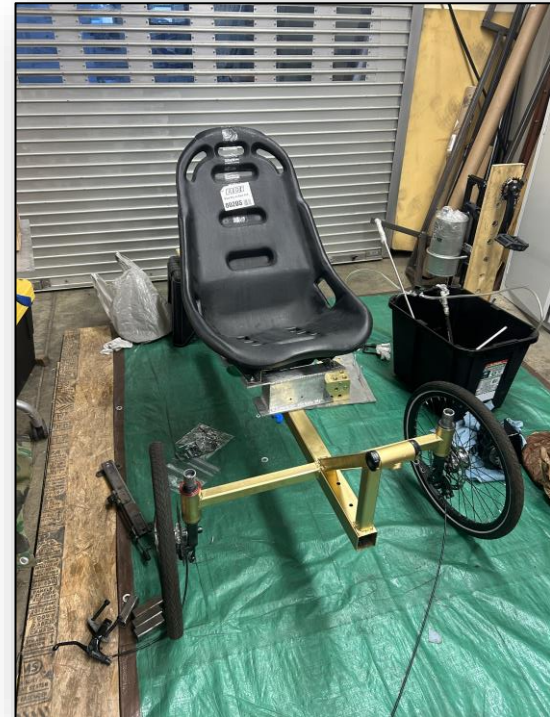


- Handlebars were also cut and welded on campus
 - Water-TIG for welding
 - Challenges of welding aluminum discussed in future slide
 - 90° vice for tube welding used for handle pieces



Seat & Steering

- Sourced a new seat with retrofitted attachment to the frame
 - Lightweight, comfortable, and easy to mount
 - Removed excess parts and drilled new holes
- Ackermann steering recycled from last team
 - Worked well previously, decided to use it again



Hydraulics

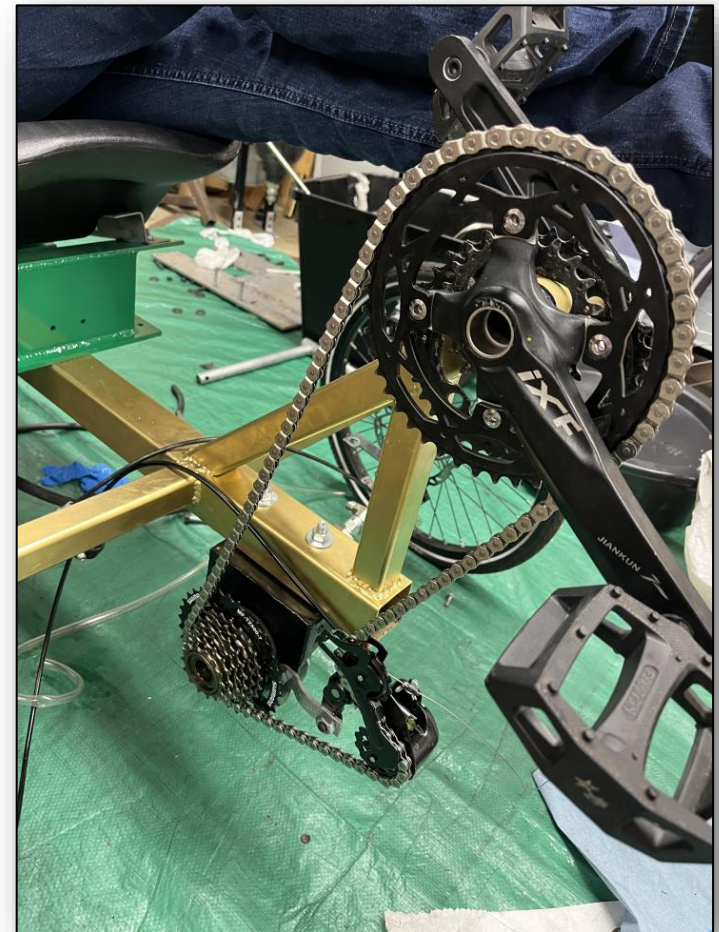


- All Hydraulic components were sourced or reused; none were made in house.
- Contractors Maintenance in San Luis Obispo, cut all hydraulic lines to length and provided fittings.
- New attachment brackets were made.



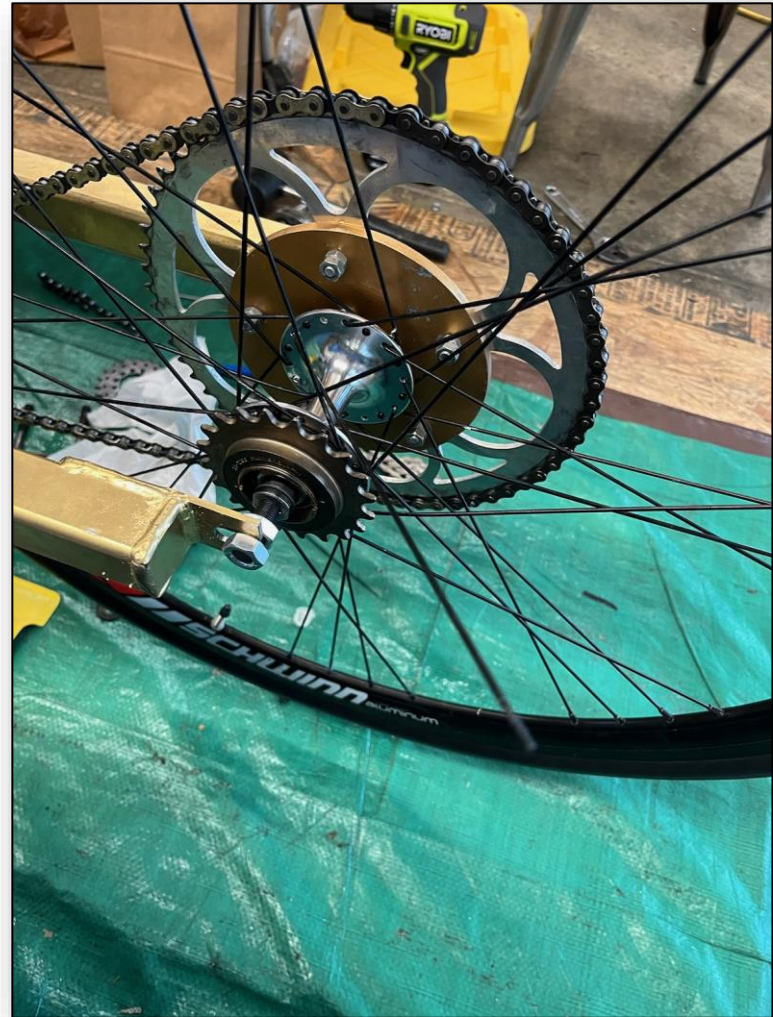
Front Power Transfer

- Interchangeable sprocket attached to the pedals
- 7-speed cassette
- Custom-mounted derailleur
- Shifter connected to our pneumatic system



Rear Power Transfer

- Flip-flop hub facilitating both free and fixed-wheel sprockets



Pneumatic Shifting



Electronics



Cal Poly
Fluid Power Interface

Drive Mode : Direct CAN Status : Not Connected

Accumulator Pressure [psi] 0

Speed [mph] 0.0

Circuit Plot Gallery Drive Mode

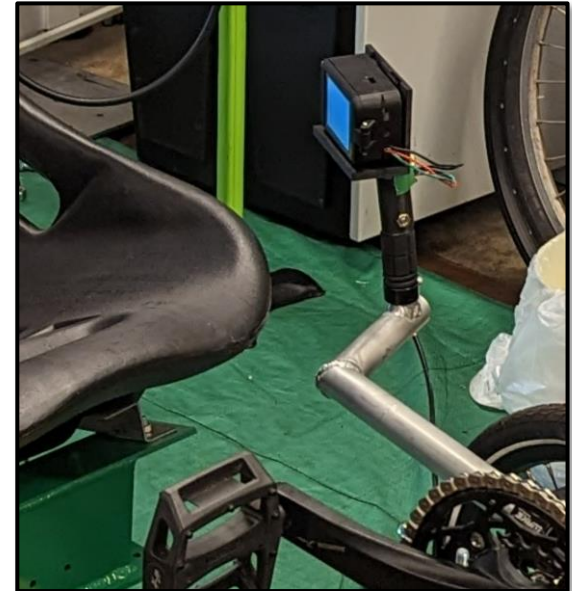
Hydraulic Circuit

Direct = Active

Drive Mode Select

Direct Drive

Direct Regen/Charge Boost

The interface displays real-time data and control options. It includes a gear icon, a lightning bolt icon, and a question mark icon. The drive mode is set to 'Direct' and the CAN status is 'Not Connected'. Two bar graphs show 'Accumulator Pressure [psi]' at 0 and 'Speed [mph]' at 0.0. Below these are icons for 'Circuit', 'Plot', 'Gallery', and 'Drive Mode'. The 'Hydraulic Circuit' section shows a schematic diagram with red arrows indicating flow direction and a legend where a red square represents an active component. The 'Drive Mode Select' section shows three toggle switches: 'Direct' (green, active), 'Regen/Charge' (red, inactive), and 'Boost' (red, inactive).



Problems and Solutions

Problems encounter during manufacturing and testing and how they were addressed.

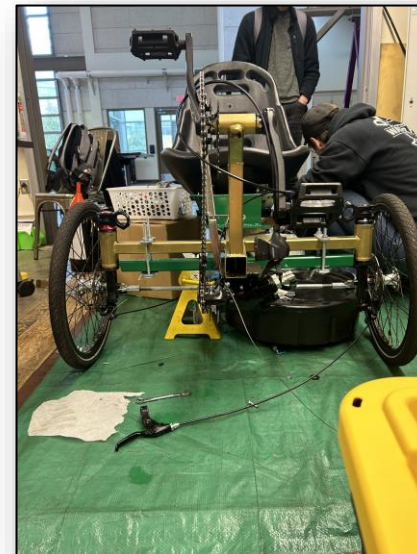
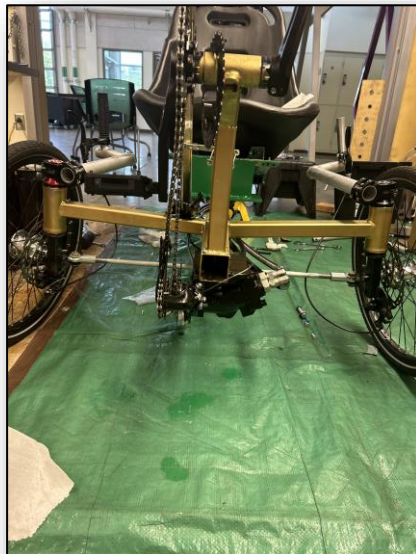
Testing



- Simulated each of the events
- Experimented with pre-charge variation
- Experienced numerous problems while testing

Front Legs Weld Yield

- Front legs yielded (V-shape)
 - Insufficient penetration when welding materials
- Needed a quick and non-invasive solution
 - Added additional beam below frame
 - Attached and bent back to shape using plates and bolts



Aluminum Welding



- TIG welding Aluminum proved to be more difficult than expected
 - Careful amperage calibration to avoid burnout
 - Thin walls
- Motor bracket required fillet welds
 - Difficult to keep oxide layer off before welding
- Solution: Asked an experienced welder on campus to weld the most difficult joints
 - Special thanks to Bryan Lutz for doing this for us

Before:



After:



Rear Wheel Spokes



Hydraulics



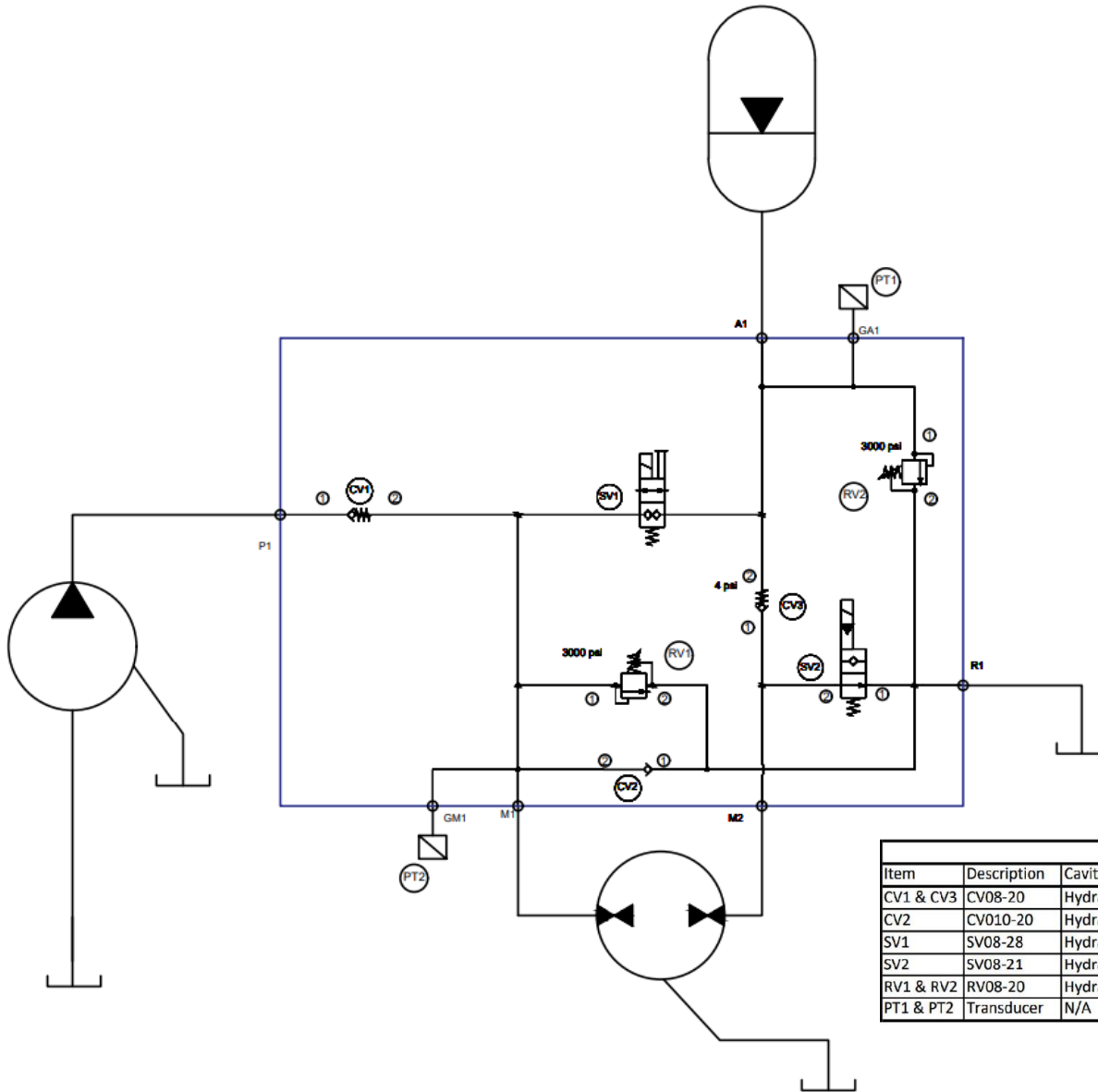
PROBLEM: MOTOR FAILED
UNDER LOADING



SOLUTION: CYCLING MOTOR



CAL POLY



Cal Poly FPVC Valves			
Item	Description	Cavity	Note
CV1 & CV3	CV08-20	Hydraforce VC-08-20 or Equivalent	Cavity Only, Using cartridge from previous year
CV2	CV010-20	Hydraforce VC-08-20 or Equivalent	Cavity Only, Using cartridge from previous year
SV1	SV08-28	Hydraforce VC-08-20 or Equivalent	Cavity Only, Using cartridge from previous year
SV2	SV08-21	Hydraforce VC-08-20 or Equivalent	Cavity Only, Using cartridge from previous year
RV1 & RV2	RV08-20	Hydraforce VC-08-20 or Equivalent	Cavity Only, Using cartridge from previous year
PT1 & PT2	Transducer	N/A	Attaches to a SAE-6 port

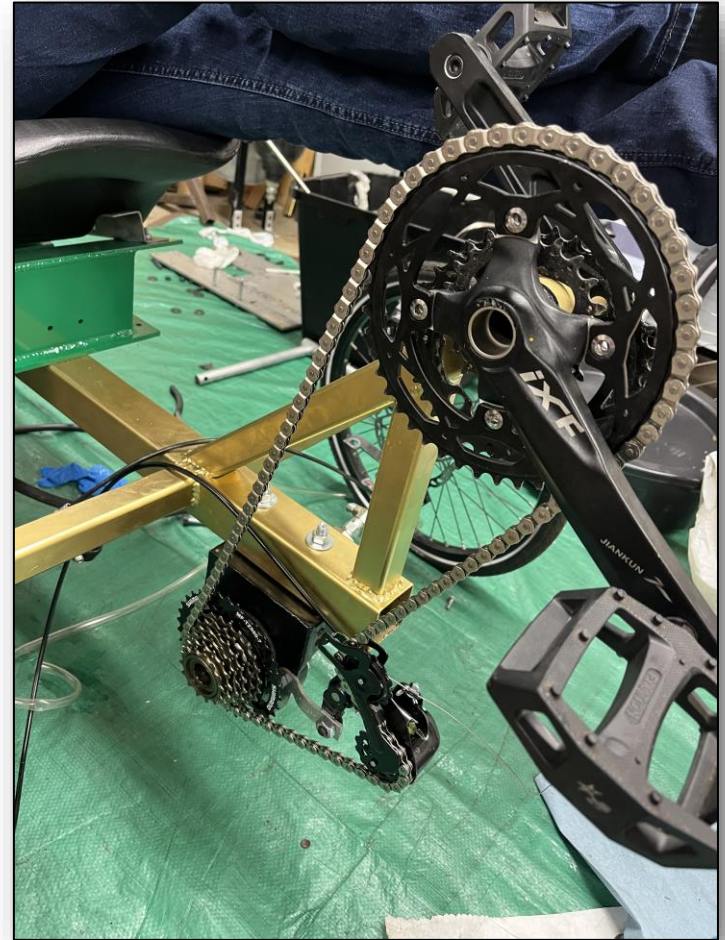
Pneumatic Consistency

- Replace Regulator
- Permanent connection from actuators to paddles
- Mechatronic control system



Shifting Limitations

- 7-speed system was too ambitious
 - Difficulty up-shifting
 - Chain angle
- Derailleur positioning



Gearing



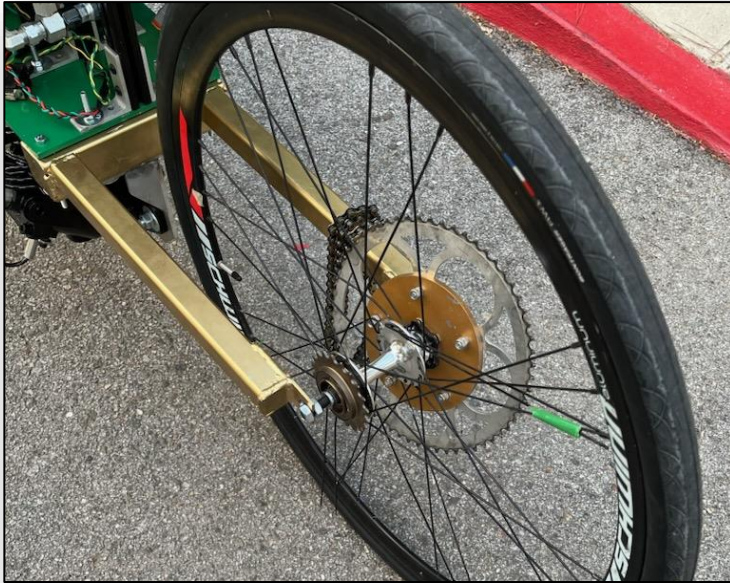
Problem: Gear ratios prevented uphill motion.



Solution: Implementation of new gears



Gearing Cont.





Reflection

Improvements and lessons

Hydraulics



- Improvements:
 - Nitrogen Pre-charge tuning
 - Hardlines and Routing
- Lessons:
 - Assembly takes time
 - Understanding Circuit logic and how careful design contributes to operation and testing
 - The importance of careful planning



Chassis



- Identify potential hang-ups early
 - Isolate aspects of design/manufacturing processes that are unclear, then investigate as soon as possible
 - Ex: welding aluminum or manufacturing space constraints
- Don't be afraid to ask for help
 - Asking shop techs, experienced welders, and faculty for assistance can greatly improve overall quality of chassis and reduce time spent designing/manufacturing
- Rule of Pi
 - Time taken for completion = initial time estimated * π
 - Anticipate that design/manufacturing processes will take longer than initially expected



Front Power Train Improvements



- Improvements:
 - Fewer ratios
 - Better derailleur positioning
- Lessons:
 - Chain angle
 - Huge variety of bike components
 - Importance of early testing



Rear Power Train Improvements



- Improvements:
 - Bolted connection for fixed sprocket
 - Stronger wheel construction
- Lessons:
 - Early stress testing
 - Consulting industry experts



Pneumatic Improvements



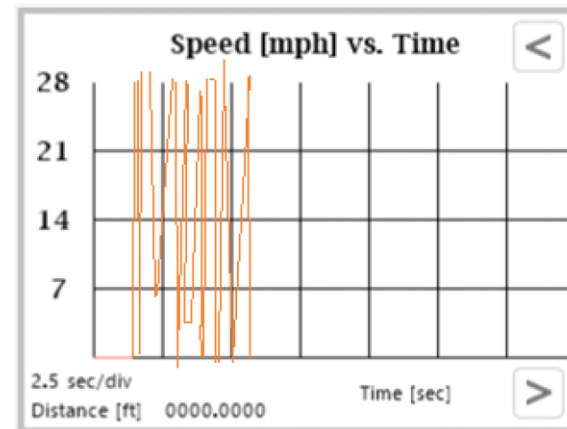
- Improvements:
 - Replace Regulator
 - Permanent actuator connections
- Lessons:
 - Scope creep



Electronic Improvements



- Simultaneous pressure readings
- Local averaging on speed sensor
- Integration of Pneumatics





Sponsors

Questions?

Slide Bank Start



Gearing Analysis



- Original Ratio (OR): .6
- New Ratio (NR): .375
- Motor pressure drop ~700psi
- OR flat: 1522psi
- NR flat: 1214psi
- OR Competition Grade: 2298psi
- NR Competition Grade: 1662psi
- Testing indicates operator can generate ~1800psi at motor inlet.

Start up Torque (Old Gear)

```
M_vehicle = 9.31; %slug bike and rider
r = 1.208; %wheel radius in ft
a_start = 1; %ft/s/s target acceleration
F_load = M_vehicle*a_start; %Force to move bike
```

```
%flat ground
T_Start = N_2*F_load*r %Torque on the motor
```

```
T_Start = 6.7479
```

```
P_motor = T_Start/T_psi %Pressure to turn motor in psi
```

```
P_motor = 822.9132
```

```
% 1% Grade (.5729 theta)
F_load2 = M_vehicle*a_start + M_vehicle*32*sind(.5729);
T_Start2 = N_2*F_load2*r; %Torque on the motor
P_motor2 = T_Start2/T_psi %Pressure to turn motor in psi
```

```
P_motor2 = 1.0862e+03
```

```
% 2.7% Grade (1.56 theta)
F_load3 = M_vehicle*a_start + M_vehicle*32*sind(1.56);
T_Start3 = N_2*F_load3*r %Torque on the motor
```

```
T_Start3 = 12.6264
```

```
P_motor3 = T_Start3/T_psi %Pressure to turn motor in psi
```

```
P_motor3 = 1.5398e+03
```

```
% 4% Grade (2.3 theta)
F_load4 = M_vehicle*a_start + M_vehicle*32*sind(2.3);
T_Start4 = N_2*F_load4*r; %Torque on the motor
P_motor4 = T_Start4/T_psi %Pressure to turn motor in psi
```

```
P_motor4 = 1.8797e+03
```

```
%Pressure increase from 0% to 2.7%
P_increase = P_motor3-P_motor
```

```
P_increase = 716.8896
```

Start up Torque (New Gear)

```
M_vehicle = 9.31; %slug bike and rider
r = 1.208; %wheel radius in ft
a_start = 1; %ft/s/s target acceleration
F_load = M_vehicle*a_start; %Force to move bike
```

```
%flat ground
T_Start = N_2*F_load*r %Torque on the motor
```

```
T_Start = 4.2174
```

```
P_motor = T_Start/T_psi %Pressure to turn motor in psi
```

```
P_motor = 514.3207
```

```
% 1% Grade (.5729 theta)
F_load2 = M_vehicle*a_start + M_vehicle*32*sind(.5729);
T_Start2 = N_2*F_load2*r; %Torque on the motor
P_motor2 = T_Start2/T_psi %Pressure to turn motor in psi
```

```
P_motor2 = 678.8840
```

```
% 2.7% Grade (1.56 theta)
F_load3 = M_vehicle*a_start + M_vehicle*32*sind(1.56);
T_Start3 = N_2*F_load3*r %Torque on the motor
```

```
T_Start3 = 7.8915
```

```
P_motor3 = T_Start3/T_psi %Pressure to turn motor in psi
```

```
P_motor3 = 962.3768
```

```
% 4% Grade (2.3 theta)
F_load4 = M_vehicle*a_start + M_vehicle*32*sind(2.3);
T_Start4 = N_2*F_load4*r; %Torque on the motor
P_motor4 = T_Start4/T_psi %Pressure to turn motor in psi
```

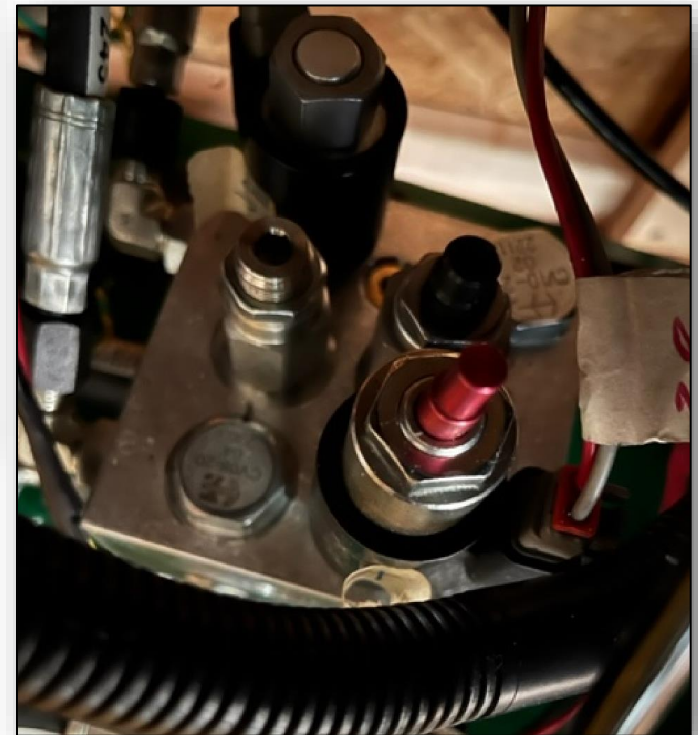
```
P_motor4 = 1.1748e+03
```

```
%Pressure increase from 0% to 2.7%
P_increase = P_motor3-P_motor
```

```
P_increase = 448.0560
```



Manifold Pictures



Hydraulic Attachments



Accumulator/Reservoir Column was reused

Pump bracket was reused

New Motor bracket

New Manifold mounting plate



Complete Display HMI

The HMI interface for Cal Poly Fluid Power Interface includes the following components:

- Header:** Cal Poly Fluid Power Interface logo and status icons (gear, lightning bolt, question mark).
- Status:** Drive Mode: Direct, CAN Status: Not Connected.
- Accumulator Pressure [psi]:** A bar graph showing 0 psi.
- Speed [mph]:** A bar graph showing 0.0 mph.
- Navigation:** Circuit, Plot, Gallery, and Drive Mode icons.
- Documentation Wiki:** A QR code for more information, installed on 4/01/23.
- Drive Mode Select:** A panel with three toggle switches: Direct (green, active), Regen/Charge (red, inactive), and Boost (red, inactive).
- Hydraulic Circuit:** A detailed schematic diagram of the hydraulic system, labeled "Direct".
- Speed [mph] vs. Time:** A graph with a y-axis from 0 to 28 mph and an x-axis for Time [sec].
- Vehicle Render:** A photograph of the physical vehicle, credited to Connor G, Milo K, Joshua R, Marius T, and Yael V.

3 Adapters For Interfacing



Component Interfacing

